

### Name of Exp.: The forearm as a lever

**The Aim:** -----

#### Theory

The forearm can be considered as a simple lever, actually a **third-class lever**. The pivot (or **fulcrum**) is at the elbow joint, the load is held in the palm of the hand and the **effort** is applied in the **biceps muscle**. In the arrangement shown in the figures, the forearm is horizontal and the force in the biceps muscle acts vertically. The system is in equilibrium for which:

$$\Sigma F_i = 0 \text{ (where } F_i \text{ are the forces)}$$

$$\Sigma \tau_i = 0 \text{ (where } \tau_i \text{ are torques about any given point)}$$

In Fig.(1),

$a_e$  is the arm of the effort ( $F$ ),

$a_m$  is the arm of the weight of the forearm ( $mg$ ),

$a_l$  is the arm of the load ( $W$ ),

$F$  is the force the biceps muscle exerts to hold the forearm ( $mg$ ) and its load ( $W$ ),

$R$  is the resistance force at the pivot 0 (fulcrum).

The forces in Fig.(1) form a system of parallel forces where,

$$F = W + mg + R \tag{1}$$

From the diagram and taking torques about the fulcrum (point 0):

Anticlockwise torque:  $\tau_{acloc} = \text{effort} \times a_e = F \times a_e$

Clockwise torques:  $\tau_{cloc} = mg \times a_m + W \times a_l$

With the arm being at equilibrium, we have:

$$\tau_{acloc} = \tau_{cloc}$$

Thus, the effort in biceps muscle to support the forearm and the load  $W$  in the hand is:

$$F = \frac{mga_m + Wa_l}{a_e} \tag{2}$$

The mechanical advantage (M.A.) is defined as:

$$M.A = \frac{\text{Output Force}}{\text{Input Force}} \tag{3}$$

$$M.A = \frac{\text{Input arm force}}{\text{Output arm force}} \tag{4}$$

#### Procedure

1. For a fixed  $a_l$ , change  $W$  and measure the effort  $F$  that makes the lever horizontal. Record as in **Table 1**. Plot a graph of  $F$  against  $W$ . Plot a graph of M.A. (Eq.3) against  $W$ .
2. For a fixed  $W$ , change  $a_l$  and measure the effort  $F$  that makes the lever horizontal. Record as in **Table 2**. Plot a graph of  $F$  against  $a_l$ . Plot a graph of M.A. (Eq.4) against  $a_l$ .
3. Discuss your results.

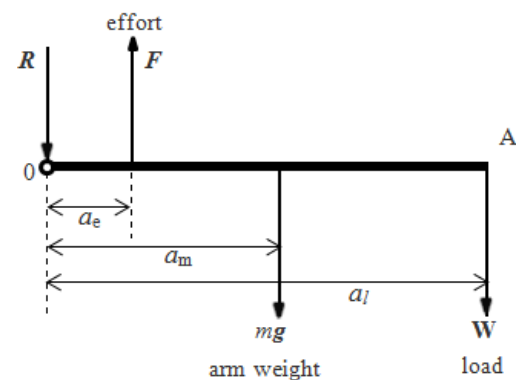
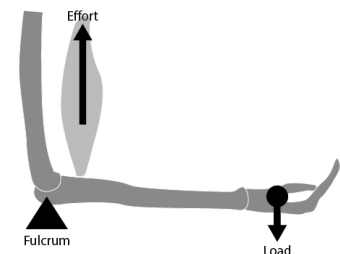


Fig.(1) The lever (arm) OA is kept horizontal.

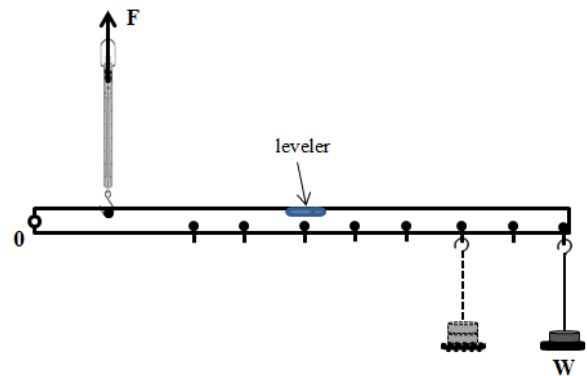


Fig.(2) Experiment setup.

$a_e = \dots\dots\dots \text{ m}, \quad a_m = \dots\dots\dots \text{ m}, \quad m = 241\text{ gm}, \quad mg = \dots\dots\dots \text{ N},$

**Table 1** Constant Load's Arm ( $a_l$ )

$a_l = \dots\dots\dots \text{ cm} = \dots\dots\dots \text{ m}$

Load W (gm)	Load W (N)	Effort Force, F (N)	M.A. Eq.(3)

**Table 2** Constant Load (W)

$W = \dots\dots\dots \text{ gm} = \dots\dots\dots \text{ N}$

Load distance $a_l \times 10^{-3}$ (m)	Effort Force, F (N)	M.A. Eq.(4)

**Questions**

1. What is the effort? **Ans.:**
  
2. Consider the human forearm as a lever with the elbow as the fulcrum. When a body of given weight is held in the hand, the force exerted by the muscles on the arm is:
 

(a) less than the weight.      (b) the same as the weight.      (c) greater than the weight.
3. Define the third-class lever. **Ans.:**
  
4. Define the first-class lever. **Ans.:**
  
5. Define the second-class lever. **Ans.:**
  
6. What are the advantage(s) of third class levers? **Ans.:**
  
7. Define the mechanical advantage of a third-class lever. **Ans.:**
  
8. What are the sources of error? How can you reduce them? Explain.